# Shift-invariant spaces of tempered distributions and $L_{p}$-functions 

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#### Abstract

This paper studies the structure of shift-invariant spaces. A characterization for the univariate shift-invariant spaces of tempered distributions is given. In $L_{p}$ case, an inclusive relation in terms of Fourier transform is established. (C) 2003 Elsevier Science (USA). All rights reserved.


Keywords: Shift-invariant space; Semi-convolution; Toeplitz theorem

## 1. Introduction

This paper studies the structure of shift-invariant spaces generated by finitely many compactly supported distributions.

A linear space $S$ of distributions is shift-invariant if, for any $\phi \in S$ and any $\alpha \in \mathbb{Z}^{s}$, $\phi(\cdot-\alpha) \in S$.

The space $\mathscr{S}\left(\mathbb{R}^{S}\right)$ of rapidly decreasing functions is the set of all infinitely differentiable functions $t$ such that, for any polynomial $p(x)$ and $\alpha \in \mathbb{Z}_{+}^{s}$,

$$
\left|p(x) \partial^{\alpha} t(x)\right| \rightarrow 0, \quad|x| \rightarrow \infty .
$$

The dual space $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ is the space of tempered distributions. Similarly, $\mathscr{S}\left(\mathbb{Z}^{s}\right) \subseteq \ell\left(\mathbb{Z}^{s}\right)$ consists of all sequences that decay faster than the reciprocal of any

[^0]polynomial sequence, where $\ell\left(\mathbb{Z}^{s}\right)$ is the set of all complex valued sequences defined on $\mathbb{Z}^{s}$. A sequence $b$ is in $\mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right)$, the dual space of $\mathscr{S}\left(\mathbb{Z}^{S}\right)$, if and only if $b$ is of polynomial growth, i.e., there exists a polynomial $p$ satisfying $|b(\alpha)| \leqslant|p(\alpha)|, \alpha \in \mathbb{Z}^{s}$.

For a distribution $\phi$ and a sequence $b \in \ell\left(\mathbb{Z}^{s}\right)$, the semi-convolution $\phi *^{\prime} b$ is defined by

$$
\phi *^{\prime} b=\sum_{\alpha \in \mathbb{Z}^{s}} b(\alpha) \phi(\cdot-\alpha) .
$$

It is well defined in case either $\phi$ is compactly supported or $b \in \ell_{0}\left(\mathbb{Z}^{s}\right)$, where $\ell_{0}\left(\mathbb{Z}^{s}\right)$ is the subspace of finitely supported sequences in $\ell\left(\mathbb{Z}^{s}\right)$. In both cases, it is clear that $\phi *^{\prime} b \in \mathscr{D}^{\prime}\left(\mathbb{R}^{s}\right)$, the space of distributions on $C_{0}^{\infty}\left(\mathbb{R}^{s}\right)$ of compactly supported and infinitely differentiable functions.

Throughout this paper we assume that $\Phi$ is a finite set consisting of $\phi_{j} \in \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right), j=1, \ldots, m$. We define the linear space $S_{0}(\Phi)$ as the smallest shiftinvariant space containing $\Phi$, that is,

$$
S_{0}(\Phi)=\left\{\sum_{1 \leqslant j \leqslant m} \phi_{j} *^{\prime} b_{j}: b_{j} \in \ell_{0}\left(\mathbb{Z}^{s}\right), \quad 1 \leqslant j \leqslant m\right\} .
$$

For $1 \leqslant p \leqslant \infty$, by $L_{p}\left(\mathbb{R}^{s}\right)$ we denote the Banach space of all complex valued measurable functions on $\mathbb{R}^{s}$ such that $\|f\|_{p}<\infty$, where

$$
\|f\|_{p}:=\left(\int_{\mathbb{R}^{s}}|f(x)|^{p} d x\right)^{1 / p}, \quad 1 \leqslant p<\infty
$$

and $\|f\|_{\infty}$ is the essential supremum of $f$ on $\mathbb{R}^{s}$. The Fourier transform $\hat{f}$, for $f \in L_{1}\left(\mathbb{R}^{s}\right)$, is defined by

$$
\hat{f( }(\omega)=\int_{\mathbb{R}^{s}} f(x) e^{-i x \omega} d \omega, \quad \omega \in \mathbb{R}^{s}
$$

The Fourier transform of a distribution in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ is defined by duality. It is well known that the Fourier transform of a compactly supported distribution can be extended to an entire function of $z \in \mathbb{C}^{s}$.

For compactly supported distributions $\phi_{j} \in \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right), j=1, \ldots, m$, the shiftinvariant space $S(\Phi) \subseteq \mathscr{D}^{\prime}\left(\mathbb{R}^{S}\right)$ is given by

$$
S(\Phi)=\left\{\sum_{1 \leqslant j \leqslant m} \phi_{j} *^{\prime} b_{j}: b_{j} \in \ell\left(\mathbb{Z}^{s}\right), \quad 1 \leqslant j \leqslant m\right\} .
$$

Further, if $\Phi$ consists of finitely many functions in $L_{p}\left(\mathbb{R}^{s}\right)$, denote by $S_{p}(\Phi)$ the closure of $S_{0}(\Phi)$ in $L_{p}\left(\mathbb{R}^{S}\right)$. It is the smallest closed shift-invariant space in $L_{p}\left(\mathbb{R}^{S}\right)$ that contains $\Phi$.

It is a meaningful problem, for a shift-invariant subspace $S \subseteq S(\Phi)$, to characterize the elements of $S$. The following result on this direction is due to de Boor et al. [2],
which holds for any finite set $\Phi \subseteq L_{2}\left(\mathbb{R}^{s}\right)$.

$$
\begin{equation*}
S_{2}(\Phi)=\left\{f \in L_{2}\left(\mathbb{R}^{s}\right): \hat{f}=\sum_{1 \leqslant j \leqslant m} \hat{\phi}_{j} a_{j}, a_{j} \text { is } 2 \pi \mathbb{Z}^{s} \text {-periodic, } 1 \leqslant j \leqslant m\right\} . \tag{1.1}
\end{equation*}
$$

The characterization (1.1) plays an important role in wavelet analysis as well as the approximation order by $S_{2}(\Phi)$, see [1-4] etc. In [6], Jia gave another proof of (1.1). It was proved in [6] that, for $\Phi \subseteq L_{p}\left(\mathbb{R}^{s}\right), S(\Phi) \cap L_{p}\left(\mathbb{R}^{s}\right)$ is closed in $L_{p}\left(\mathbb{R}^{s}\right)$ and that $S(\Phi) \cap L_{2}\left(\mathbb{R}^{s}\right)=S_{2}(\Phi)$ for $\Phi \subseteq L_{2}\left(\mathbb{R}^{s}\right)$.

It is well known that, for any $p \in[1,2]$ and any function $f \in L_{p}\left(\mathbb{R}^{s}\right)$, the Fourier transform $\hat{f} \in L_{p^{\prime}}\left(\mathbb{R}^{s}\right)$, where $p^{\prime}$ is the conjugate number of $p, 1 / p+1 / p^{\prime}=1$. The analogue of the subspace in the right-hand side of (1.1) is defined as follows:

$$
\begin{equation*}
X_{p}(\Phi)=\left\{f \in L_{p}\left(\mathbb{R}^{s}\right): \hat{f}=\sum_{1 \leqslant j \leqslant m} \hat{\phi}_{j} a_{j}, a_{j} \text { is } 2 \pi \mathbb{Z}^{s} \text {-periodic, } 1 \leqslant j \leqslant m\right\} \tag{1.2}
\end{equation*}
$$

In this paper, we are interested in the shift-invariant spaces in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ and $L_{p}\left(\mathbb{R}^{s}\right)$, respectively. When $\Phi$ consists of compactly supported distributions in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$, we give a characterization in Section 2 for $f \in \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ by the coefficients $b_{j}(\alpha), \alpha \in \mathbb{Z}^{s}, 1 \leqslant j \leqslant m$, provided that either $s=1$ or the shifts of $\Phi$ are stable (see below for the definition of stable). For $\Phi \subseteq L_{p}\left(\mathbb{R}^{s}\right), \quad 1 \leqslant p \leqslant 2$, consisting of compactly supported functions, we establish in Section 3 that $S(\Phi) \cap L_{p}\left(\mathbb{R}^{s}\right) \subseteq X_{p}(\Phi)$. As a by product we present a proof of the equality $S(\Phi) \cap L_{2}\left(\mathbb{R}^{S}\right)=S_{2}(\Phi)$ for $\Phi \subseteq L_{2}\left(\mathbb{R}^{S}\right)$.

There are two methods to describe the structure of shift-invariant spaces. Fourier transforms of $\phi_{j}, 1 \leqslant j \leqslant m$, have been used extensively and mainly to characterize the shift-invariant subspaces in $L_{2}\left(\mathbb{R}^{s}\right)$. Another method is to use semi-convolution. It turns out that the semi-convolution is a powerful tool to deal with the non- $L_{2}$ case as well as $L_{2}$ case. Our method is a combination of them.

## 2. Shift-invariant subspaces of tempered distributions

In this section we characterize the shift-invariant subspaces of $\mathscr{S}^{\prime}\left(\mathbb{R}^{S}\right)$ in terms of coefficients in semi-convolution.

We first introduce some notions and results about the linear independence and stability of the shifts of $\Phi$. Let $\Phi=\left\{\phi_{j}\right\}_{1 \leqslant j \leqslant m}$ be a finite set consisting of compactly supported distributions. The shifts of $\Phi$ are linearly independent (stable, respectively) if for any $b_{j} \in \ell\left(\mathbb{Z}^{s}\right)\left(\ell_{\infty}\left(\mathbb{Z}^{s}\right)\right.$, respectively), $1 \leqslant j \leqslant m$,

$$
\begin{equation*}
\sum_{1 \leqslant j \leqslant m} \sum_{\alpha \in \mathbb{Z}^{s}} b_{j}(\alpha) \phi_{j}(\cdot-\alpha)=0 \Rightarrow b_{j}(\alpha)=0, \quad 1 \leqslant j \leqslant m, \quad \alpha \in \mathbb{Z}^{s} \tag{2.1}
\end{equation*}
$$

Let $\Phi$ consist of finitely many compactly supported distributions $\phi_{j} \in \mathscr{S}^{\prime}\left(\mathbb{R}^{S}\right)$, $1 \leqslant j \leqslant m$. The restriction of $S(\Phi)$ to the cube $\Omega=(-1,1)^{s}$ is a finite dimensional subspace of $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$. There exists a basis $\psi_{k}, \quad 1 \leqslant k \leqslant n$, of $\left.S(\Phi)\right|_{\Omega}$. For any $b_{k} \in \ell\left(\mathbb{Z}^{S}\right)$, $\sum_{1 \leqslant k \leqslant n} \psi_{k} *^{\prime} b_{k}=0$ if and only if $b_{k}=0,1 \leqslant k \leqslant n$.

Obviously, there exists $m \times n$ finitely supported sequences $c_{j k}, 1 \leqslant j \leqslant m, \quad 1 \leqslant k \leqslant n$, such that for any $\alpha \in \mathbb{Z}^{s}$

$$
\begin{equation*}
\left.\phi_{j}(\cdot+\alpha)\right|_{\Omega}=\sum_{1 \leqslant k \leqslant n} c_{j k}(\alpha) \psi_{k} . \tag{2.2}
\end{equation*}
$$

Define the Laurent polynomials as

$$
\begin{equation*}
g_{j k}(z)=\sum_{\alpha \in \mathbb{Z}^{s}} c_{j k}(\alpha) z^{-\alpha}, \quad z \in(\mathbb{C} \backslash\{0\})^{s}, \quad 1 \leqslant j \leqslant m, \quad 1 \leqslant k \leqslant n \tag{2.3}
\end{equation*}
$$

and the matrix

$$
\begin{equation*}
G(z)=\left(g_{j k}(z)\right)_{1 \leqslant j \leqslant m, 1 \leqslant k \leqslant n}, \quad z \in(\mathbb{C} \backslash\{0\})^{s} \tag{2.4}
\end{equation*}
$$

Recall from [7] that the linear independence (stability, respectively) of the shifts of $\Phi$ is equivalent to the fact that, for any $z \in(\mathbb{C} \backslash\{0\})^{s}\left(z \in \mathbb{T}^{s}\right.$, respectively) the matrix $G(z)$ has rank $m$.

The difference operator is a convenient tool. Given $\alpha \in \mathbb{Z}^{s}$, the operator $\tau^{\alpha}$ on $\ell\left(\mathbb{Z}^{s}\right)$ is defined by $\tau^{\alpha} f=f(\cdot+\alpha), f \in \ell\left(\mathbb{Z}^{S}\right)$. A Laurent polynomial $p(z)=\sum_{\alpha} c(\alpha) z^{\alpha}$ induces a difference operator $p(\tau)=\sum_{\alpha} c(\alpha) \tau^{\alpha}$.

Denote by $V$ the set of all the distributions that have the following representation: there exist some $f_{k} \in \ell\left(\mathbb{Z}^{s}\right), \quad 1 \leqslant k \leqslant n$, such that for all $\alpha \in \mathbb{Z}^{s}$,

$$
\begin{equation*}
\left.f(\cdot+\alpha)\right|_{\Omega}=\sum_{1 \leqslant k \leqslant n} f_{k}(\alpha) \psi_{k} \tag{2.5}
\end{equation*}
$$

Clearly, $S(\Phi) \subseteq V$. Moreover, a distribution $f \in V$ with representation (2.5) belongs to $S(\Phi)$ if and only if the system

$$
\begin{equation*}
\sum_{1 \leqslant j \leqslant m} g_{j k}(\tau) b_{j}=f_{k}, \quad 1 \leqslant k \leqslant n \tag{2.6}
\end{equation*}
$$

is solvable for $b_{j}, 1 \leqslant j \leqslant m$. The details are referred to, for example, [7].
Based on Toeplitz Theorem, Jia [5] characterized the solvability of (2.6) as follows.
Lemma 1 (Jia [5]). Assume that for any pair of $(j, \beta)$, there are only finitely many pairs of $(k, \alpha)$ such that $c_{j k}(\alpha-\beta) \neq 0$. Then the system of difference equations (2.6) is solvable if and only if it satisfies that, for any Laurent polynomials $q_{k}(z), 1 \leqslant k \leqslant n$,

$$
\begin{equation*}
\sum_{1 \leqslant k \leqslant n} g_{j k} q_{k}=0 \quad \forall 1 \leqslant j \leqslant m \Rightarrow \sum_{1 \leqslant k \leqslant n} q_{k}(\tau) f_{k}=0 . \tag{2.7}
\end{equation*}
$$

Our first result is a characterization of $f \in V$ to be a distribution in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ in terms of its coefficient sequences $f_{k}, 1 \leqslant k \leqslant n$. Its proof is elementary and, therefore, omitted.

Lemma 2. Let $f \in V$ be as given in (2.6) with the coefficients $f_{k}(\alpha), 1 \leqslant k \leqslant n, \alpha \in \mathbb{Z}^{s}$. Then $f \in \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ if and only if for any $k, 1 \leqslant k \leqslant n, f_{k} \in \mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right)$.

The following lemma is a well-known result.
Lemma 3. For any nonzero univariate Laurent polynomial $q(z)$ and a sequence $g \in \mathscr{S}^{\prime}(\mathbb{Z})$, the difference equation $q(\tau) a=g$ has solution $a \in \mathscr{S}^{\prime}(\mathbb{Z})$. The solution is unique if and only if $q(z)$ has no zero on $\mathbb{T}$.

Theorem 4. Assume that $\Phi=\left\{\phi_{j}\right\}_{1 \leqslant j \leqslant m}$ is a finite set of compactly supported distributions in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$. For univariate case, $s=1$, we have

$$
\begin{equation*}
S(\Phi) \cap \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)=\left\{f: f=\sum_{1 \leqslant j \leqslant m} \phi_{j} *^{\prime} b_{j}, b_{j} \in \mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right) 1 \leqslant j \leqslant m\right\} . \tag{2.8}
\end{equation*}
$$

Proof. It is clear that for any $b_{j} \in \mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right), \sum_{1 \leqslant j \leqslant m} \phi_{j} *^{\prime} b_{j} \in S(\Phi) \cap \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$. Assume now $f \in S(\Phi) \cap \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$. Then $f \in V$. There exist coefficient sequences $f_{k} \in \mathscr{S}^{\prime}(\mathbb{Z}), 1 \leqslant k \leqslant n$, such that (2.5) holds. As we have known that, for such $f_{k}, 1 \leqslant k \leqslant n$, the system of difference equations (2.6) is solvable for some $b_{j}, 1 \leqslant j \leqslant m$. Therefore the implication relation (2.7) holds.

We shall appeal to the results for the decompositions of (univariate) polynomial matrices to establish the solvability of (2.6) for $b_{j} \in \mathscr{S}^{\prime}(\mathbb{Z}), \quad 1 \leqslant j \leqslant m$. Recall that $G(z)$ is the Laurent polynomial matrix in (2.3). It is well known that there exist an $n \times n$ Laurent polynomial matrix $L(z)$ and a $m \times m$ Laurent polynomial matrix $R(z)$ satisfying $\operatorname{det} L(z)=\operatorname{det} R(z)=1, z \in \mathbb{C}$, and $L(z) G^{T}(z)=D^{T}(z) R(z), z \in \mathbb{C}$, where

$$
D(z)=\left(d_{j k}(z)\right)_{1 \leqslant j \leqslant m, 1 \leqslant k \leqslant n}
$$

is a Laurent polynomial matrix with the only nonzero entries $d_{j j}(z), j=1,2, \ldots, r$, and $r$ being the largest number such that there exists $r \times r$ submatrix of $G(z)$ whose determinant is not identically zero. Moreover, $d_{j j}(z)$ is a factor of $d_{j+1 j+1}(z), j=$ $1, \ldots, r-1$.

As usual, the operator $L(\tau)$ on $(\ell(\mathbb{Z}))^{n}$ is induced by matrix $L(z)$. Moreover, as Lemma 3, we may conclude that $L(\tau)$ is an invertible operator on $\left(\mathscr{S}^{\prime}(\mathbb{Z})\right)^{n}$. Similarly $R(\tau)$ is invertible on $\left(\mathscr{S}^{\prime}(\mathbb{Z})\right)^{m}$. Let $b=\left(b_{1}, \ldots, b_{m}\right)^{T}$ and $f=\left(f_{1}, \ldots, f_{n}\right)^{T}$. Then we may rewrite (2.6) as $G^{T}(\tau) b=f$. Therefore, it is obvious that (2.6) has solution $b_{j} \in \mathscr{S}^{\prime}(\mathbb{Z}), 1 \leqslant j \leqslant m$, if and only if the system of difference equations

$$
\begin{equation*}
\sum_{1 \leqslant j \leqslant m} d_{j k}(\tau) a_{j}=h_{k}, \quad 1 \leqslant k \leqslant n, \tag{2.9}
\end{equation*}
$$

has solution $a_{j} \in \mathscr{S}^{\prime}(\mathbb{Z}), \quad 1 \leqslant j \leqslant m$, where $h_{k}, \quad 1 \leqslant k \leqslant n$, are given by

$$
h=\left(h_{1}, \ldots, h_{n}\right)^{T}=L(\tau) f \in\left(\mathscr{S}^{\prime}(\mathbb{Z})\right)^{n}
$$

We first conclude that $h_{i}=0$ for $i=r+1, \ldots, n$. To this end denote

$$
L(z)=\left(l_{i k}(z)\right)_{1 \leqslant i, k \leqslant n} .
$$

Recall that all entries in the last $n-r$ rows of $D^{T}(z)$ are zero. So does $L(z) G^{T}(z)$.

This means

$$
\sum_{1 \leqslant k \leqslant n} g_{j k} l_{i k}=0 \quad \forall 1 \leqslant j \leqslant m, \quad i=r+1, \ldots, n .
$$

It follows from (2.7) that

$$
h_{i}=\sum_{1 \leqslant k \leqslant n} l_{i k}(\tau) f_{k}=0, \quad i=r+1, \ldots, n,
$$

as claimed.
By Lemma 3, for any $j, 1 \leqslant j \leqslant r$, there exists $a_{j} \in \mathscr{S}^{\prime}(\mathbb{Z})$ satisfying $d_{j j}(\tau) a_{j}=h_{j}$. Setting $\quad a_{j}=0, j=r+1, \ldots, m, \quad$ and $\quad b=\left(b_{1}, \ldots, b_{m}\right)^{T}=(R(\tau))^{-1} a$, then $b_{j} \in \mathscr{S}^{\prime}(\mathbb{Z}), \quad 1 \leqslant j \leqslant m$, satisfies (2.6). The proof is complete.

To establish equality (2.8) in multivariate case we need the stability of the shifts of $\Phi$.

Theorem 5. Assume that $\Phi=\left\{\phi_{j}\right\}_{1 \leqslant j \leqslant m}$ is a finite set of compactly supported distributions in $\mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$ with stable shifts. Then (2.8) holds for any s.

Proof. Assume that $f \in S(\Phi) \cap \mathscr{S}^{\prime}\left(\mathbb{R}^{s}\right)$. There are $n$ coefficient sequences $f_{k} \in \ell\left(\mathbb{Z}^{s}\right), 1 \leqslant k \leqslant n$, such that (2.5) holds. By Lemma $2, f_{k} \in \mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right), 1 \leqslant k \leqslant n$. Since the shifts of $\Phi$ are stable, the matrix $G(z)$ given as in (2.4) has rank $m$ for any $z \in \mathbb{T}^{s}$. The system of difference equations (2.6) satisfies (2.7) for that $f_{k}, 1 \leqslant k \leqslant n$. Similar to the proof of [6, Theorem 7.1] we can deduce that the system of difference equations (2.6) is uniquely solvable for $b_{j} \in \mathscr{S}^{\prime}\left(\mathbb{Z}^{s}\right), 1 \leqslant j \leqslant m$. We refer to [6] for the details. The proof is complete.

## 3. Shift-invariant spaces in $L_{p}\left(\mathbb{R}^{s}\right)(1 \leqslant p \leqslant 2)$

We establish in this section the inclusive relation $S(\Phi) \cap L_{p}\left(\mathbb{R}^{S}\right) \subseteq X_{p}(\Phi)$ for $\Phi \in L_{p}\left(\mathbb{R}^{s}\right), \quad 1 \leqslant p \leqslant 2$.

Assume throughout this section that the finite set $\Phi \subseteq L_{p}\left(\mathbb{R}^{s}\right), 1 \leqslant p \leqslant 2$, consists of compactly supported functions. We may consider the restriction of $S(\Phi)$ to the cube $[0,1]^{s}$, instead of $(-1,1)^{s}$ as in Section 2. Thus, in contrast to Section 2, the basis $\psi_{k}, 1 \leqslant k \leqslant n$, of $\left.S(\Phi)\right|_{[0,1]^{s}}$ can be so chosen that $\psi_{k}, 1 \leqslant k \leqslant n$, are supported on $[0,1]^{s}$. As a finite set $\Psi:=\left\{\psi_{k}\right\}_{1 \leqslant k \leqslant n}$, it satisfies that, for any numbers $c_{k} \in \mathbb{C}, 1 \leqslant k \leqslant n$,

$$
\left\|\sum_{1 \leqslant k \leqslant n} c_{k} \psi_{k}\right\|_{L_{p}[0,1]^{s}} \approx\left(\sum_{1 \leqslant k \leqslant n}\left|c_{k}\right|^{p}\right)^{1 / p}
$$

from which it follows that, for any $f_{k} \in \ell_{p}\left(\mathbb{Z}^{s}\right), 1 \leqslant k \leqslant n$,

$$
\begin{equation*}
\left\|\sum_{1 \leqslant k \leqslant n} \psi_{k} *^{\prime} f_{k}\right\|_{p} \approx\left(\sum_{1 \leqslant k \leqslant n}\left\|f_{k}\right\|_{p}\right)^{1 / p} \tag{3.1}
\end{equation*}
$$

It is always true that $S(\Phi) \subseteq S(\Psi)$. Instead of (2.2), it holds that for some $m \times n$ finitely supported sequences $c_{j k}, 1 \leqslant j \leqslant m, 1 \leqslant k \leqslant n$,

$$
\begin{equation*}
\phi_{j}=\sum_{1 \leqslant k \leqslant n} \psi_{k} *^{\prime} c_{j k}, \quad 1 \leqslant j \leqslant m \tag{3.2}
\end{equation*}
$$

Taking Fourier transform, we get

$$
\begin{equation*}
\hat{\phi}_{j}(\omega)=\sum_{1 \leqslant k \leqslant n} \hat{\psi}_{k}(\omega) g_{j k}\left(e^{i \omega}\right), \quad 1 \leqslant j \leqslant m \tag{3.3}
\end{equation*}
$$

whereas in Section $2, g_{j k}(z)=\sum_{\alpha \in \mathbb{Z}^{s}} c_{j k}(\alpha) z^{-\alpha}, \quad 1 \leqslant j \leqslant m, 1 \leqslant k \leqslant n$.
As in Section 2, an element $f=\sum_{1 \leqslant k \leqslant n} \psi_{k} *^{\prime} f_{k} \in S(\Phi)$ if and only if the system of difference equations (2.6) is solvable or, equivalently, the implication relation (2.7) holds.

Theorem 6. Let $\Phi$ be a finite set of compactly supported functions in $L_{p}\left(\mathbb{R}^{s}\right)$. Then

$$
S(\Phi) \cap L_{p}\left(\mathbb{R}^{s}\right) \subseteq X_{p}(\Phi), \quad p \in[1,2]
$$

where $X_{p}(\Phi)$ is as defined in (1.2).
Proof. Let $f \in S(\Phi) \cap L_{p}\left(\mathbb{R}^{s}\right)$. Then $f=\sum_{1 \leqslant k \leqslant n} \psi_{k} *^{\prime} f_{k}$ with $f_{k} \in l_{p}\left(\mathbb{Z}^{s}\right), 1 \leqslant k \leqslant n$, by (3.1). By Hausdorff-Young Theorem, for any $1 \leqslant k \leqslant n$, the series $\sum_{\alpha \in \mathbb{Z}^{s}} f_{k}(\alpha) e^{i \alpha \omega}$ converges in $L_{p^{\prime}}[0,2 \pi]^{s}$ to a function, say, $\tilde{f_{k}}(\omega)$, where $p^{\prime}$ is the conjugate number of $p, 1 / p+1 / p^{\prime}=1$.

On the other hand, since system (2.6) is solvable for $b_{j}, 1 \leqslant j \leqslant m$, it satisfies (2.7) by Lemma 1 . Therefore, for any Laurent polynomials $q_{k}, 1 \leqslant k \leqslant n$,

$$
\begin{equation*}
\sum_{1 \leqslant k \leqslant n} q_{k} g_{j k}=0 \forall 1 \leqslant j \leqslant m \Rightarrow \sum_{1 \leqslant k \leqslant n} q_{k}\left(e^{-i \omega}\right) \tilde{f}_{k}(\omega)=0 \quad \text { a.e. } \omega \text {. } \tag{3.4}
\end{equation*}
$$

We shall prove that, for a.e. $\omega \in[0,2 \pi]^{s}$, the following system is solvable.

$$
\begin{equation*}
\sum_{1 \leqslant j \leqslant m} g_{j k}\left(e^{i \omega}\right) a_{j}=\tilde{f_{k}}(\omega), \quad 1 \leqslant k \leqslant n \tag{3.5}
\end{equation*}
$$

Let $N$ be the largest integer such that there exists a submatrix $M(z)$ with size $N$ of $G(z)$ satisfying $\operatorname{det} M(z)$ is not identically zero. As a Laurent polynomial $\operatorname{det} M(z) \neq 0$ for a.e. $z$. Without loss of any generality, we assume

$$
M(z)=\left(g_{j k}(z)\right)_{1 \leqslant j, k \leqslant N}
$$

Given any $2 \pi \mathbb{Z}^{s}$-periodic functions $a_{j}(\omega), N+1 \leqslant j \leqslant m$, the system

$$
\begin{equation*}
\sum_{1 \leqslant j \leqslant N} g_{j k}\left(e^{i \omega}\right) a_{j}=\tilde{f_{k}}(\omega)-\sum_{N+1 \leqslant j \leqslant m} g_{j k}\left(e^{i \omega}\right) a_{j}(\omega), \quad 1 \leqslant k \leqslant N \tag{3.6}
\end{equation*}
$$

has unique solution $a_{j}:=a_{j}(\omega), 1 \leqslant j \leqslant N$, for a.e. $\omega$. Clearly, $a_{j}(\omega)$ are also $2 \pi \mathbb{Z}^{s}$ periodic functions. Therefore, $a_{j}(\omega), 1 \leqslant j \leqslant m$, solve the first $N$ equations in (3.5).

It needs to verify that $a_{j}(\omega), 1 \leqslant j \leqslant m$, satisfy the last $n-N$ equations in (3.5). In fact, for any $k_{0}, N<k_{0} \leqslant n$, by the definitions of $N$ and $M(z)$, there exist Laurent polynomials $q_{k}, 1 \leqslant k \leqslant N$, and $q_{k_{0}}$, not all zero, such that

$$
\begin{equation*}
q_{k_{0}}(z) g_{j k_{0}}(z)+\sum_{1 \leqslant k \leqslant N} q_{k}(z) g_{j k}(z)=0, \quad z \in \mathbb{T}^{s}, \quad 1 \leqslant j \leqslant m . \tag{3.7}
\end{equation*}
$$

It is clear that $q_{k_{0}}$ is not identically zero, for otherwise, the above equalities imply $\operatorname{det} M(z)=0, \quad z \in \mathbb{T}^{s}$, a contradiction. It follows from Lemma 1 and (3.4) that

$$
\begin{equation*}
\tilde{f_{k_{0}}}(\omega)=-\sum_{1 \leqslant k \leqslant N} q_{k}\left(e^{-i \omega}\right) \tilde{f}_{k}(\omega) / q_{k_{0}}\left(e^{-i \omega}\right) \quad \text { a.e. } \omega \tag{3.8}
\end{equation*}
$$

By (3.7), (3.6) and (3.8), we obtain that for a.e. $\omega$

$$
\begin{aligned}
& \sum_{1 \leqslant j \leqslant m} g_{j k_{0}}\left(e^{i \omega}\right) a_{j}(\omega) \\
& \quad=-\sum_{1 \leqslant k \leqslant N} \sum_{1 \leqslant j \leqslant m} g_{j k}\left(e^{i \omega}\right) a_{j}(\omega) q_{k}\left(e^{-i \omega}\right) / q_{k_{0}}\left(e^{-i \omega}\right) \\
& \quad=-\sum_{1 \leqslant k \leqslant N} q_{k}\left(e^{-i \omega}\right) \tilde{f_{k}}(\omega) / q_{k_{0}}\left(e^{-i \omega}\right)=\tilde{f_{k_{0}}}(\omega),
\end{aligned}
$$

as desired. It follows from equalities (3.3) and (3.5) that

$$
\begin{equation*}
\hat{f}=\sum_{1 \leqslant j \leqslant m} \hat{\phi}_{j} a_{j} \quad \text { a.e. } \omega \tag{3.9}
\end{equation*}
$$

The proof is complete.
Corollary 7 (Jia [6, Theorem 4.1]). Let $\Phi$ be a finite set of compactly supported functions in $L_{2}\left(\mathbb{R}^{S}\right)$. Then

$$
S(\Phi) \cap L_{2}\left(\mathbb{R}^{S}\right)=S_{2}(\Phi)
$$

Proof. Recall that $S_{2}(\Phi)$ is the smallest closed shift-invariant space containing $\Phi$. Since $S(\Phi) \cap L_{2}\left(\mathbb{R}^{s}\right)$ is a closed subspace of $L_{2}\left(\mathbb{R}^{s}\right)$ containing $\Phi$ [6], $S_{2}(\Phi) \subseteq S(\Phi) \cap L_{2}\left(\mathbb{R}^{S}\right)$. By Theorem 6, it suffices to establish $X_{2}(\Phi) \subseteq S_{2}(\Phi)$.

Suppose that $g \in S_{2}(\Phi)^{\perp}$, the orthogonal complement of $S_{2}(\Phi)$ in $L_{2}\left(\mathbb{R}^{s}\right)$. Then

$$
\int_{\mathbb{R}^{s}} \phi_{j}(x-\alpha) \overline{g(x)} d x=0, \quad 1 \leqslant j \leqslant m, \quad \alpha \in \mathbb{Z}^{s} .
$$

Therefore, by Parseval identity, for any $j, 1 \leqslant j \leqslant m$,

$$
\sum_{\alpha \in \mathbb{Z}^{s}} \hat{\phi}_{j}(\omega+2 \pi \alpha) \overline{\hat{g}(\omega+2 \pi \alpha)}=0 \quad \text { a.e. } \omega .
$$

For any $f \in X_{2}(\Phi)$, there are some $2 \pi \mathbb{Z}^{s}$-periodic functions $a_{j}, \quad 1 \leqslant j \leqslant m$, such that (3.9) holds. By the above equalities

$$
\sum_{\alpha \in \mathbb{Z}^{s}} \hat{f}(\omega+2 \pi \alpha) \overline{\hat{g}(\omega+2 \pi \alpha)}=0 \quad \text { a.e. } \omega .
$$

This in turn gives $\int_{\mathbb{R}^{s}} f(x) \overline{g(x)} d x=0$. Therefore, $g \in X_{2}(\Phi)^{\perp}$. It follows that $S_{2}(\Phi)^{\perp} \subseteq X_{2}(\Phi)^{\perp}$. The proof is complete.

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